

# Coarse grain models (continuous) ... potentials of mean force

So far ?

- very detailed models
  - atomistic, solvation

What are some reasonable aims ?

- given a set of coordinates
  - are these roughly correct for a protein sequence ?
  - is this more likely to be  $\alpha$ -helical or  $\beta$ -sheet ?

Should we approach this with a detailed force field ?

- maybe not

# Aims

- Why atomistic force fields / score functions are not always best
- Different levels of force fields
- Examples of coarse-grain / low-resolution force fields
- Ways to parameterise force fields
- Score functions directly from structural data
  
- later...
- extending this idea to lattice models

# History

## History

- Levitt, M and Warshel, A, Nature, 253, 694-698, Computer simulation of protein folding (1975)
- Kuntz, ID, Crippen, GM, Kollman, PA and Kimelman, D, J. Mol. Biol, 106, 983-994, Calculation of protein tertiary structure (1976)
- Levitt, M, J. Mol. Biol, 104, 59-107, A simplified representation of protein conformations for rapid simulation of protein folding (1976)
- through to today

# Problems with detailed force fields

## Time

- typical atomistic protein simulations  $10^{-9}$  to  $10^{-6}$  s
- too short for folding

## Radius of convergence

- I have coordinates where atoms are perturbed by 1 Å
  - easy to fix – atoms move quickly
- I have completely misfolded, but well packed coordinates
  - may be difficult to fix
  - what dominates ?
    - atomic packing
    - charges
    - solvation ?

Do I care about details ?

# Coarse grain / low resolution

Forget atomic details

- build something like energy which encapsulates our ideas
- example – define a function which is happiest with
  - hydrophobic residues together
  - charged residues on outside
- would this be enough ?
  - maybe / not for everything

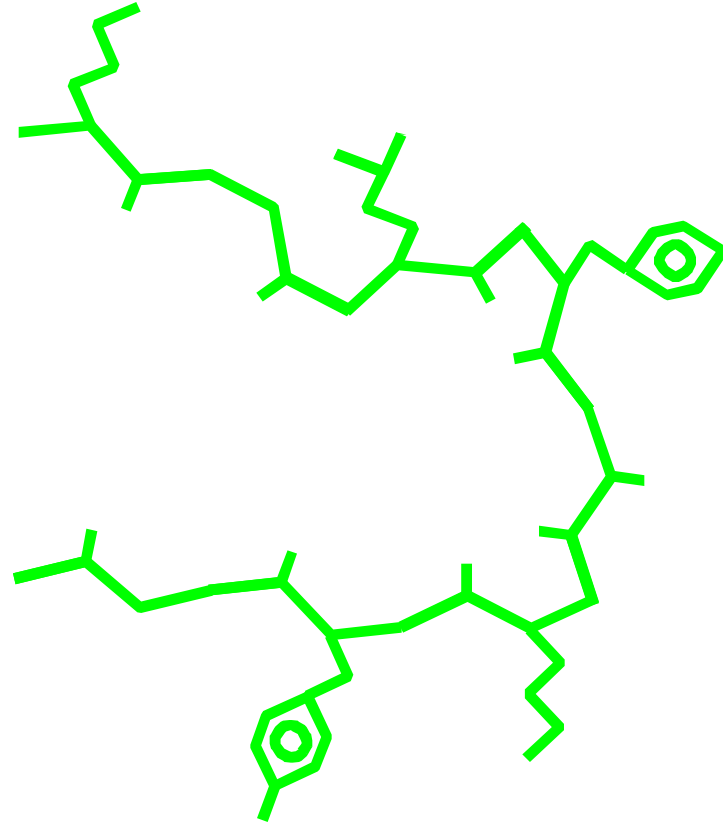
What will I need ?

- some residues like to be near each other (hydrophobic)
- residues are always some constant distance from each other
- only certain backbone angles are allowed

# General implementation (easiest)

How do we represent a protein ?

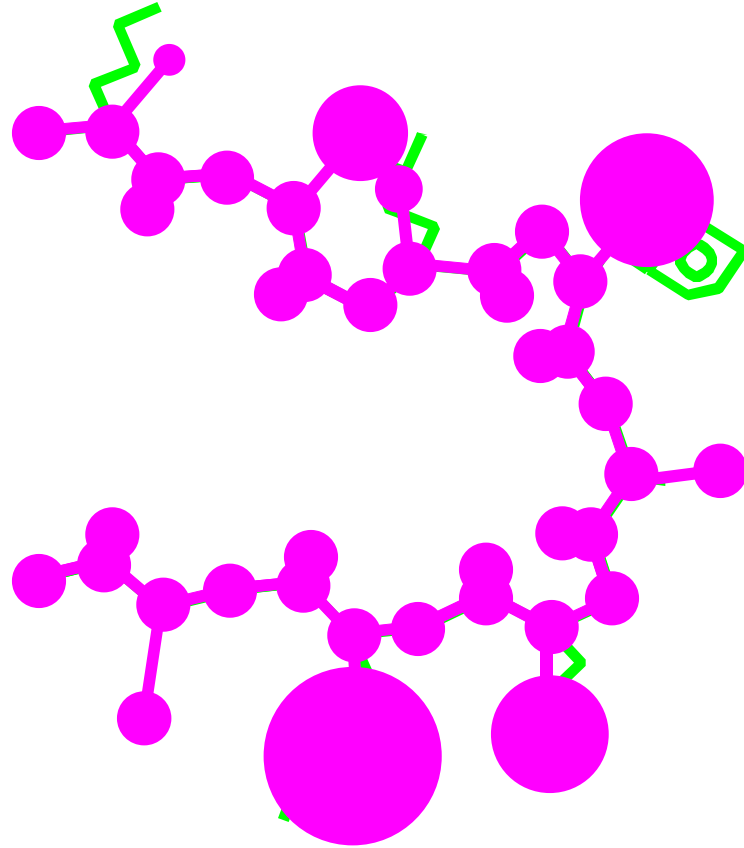
- decide on number of sites per residue



# General implementation (easiest)

How do we represent a protein ?

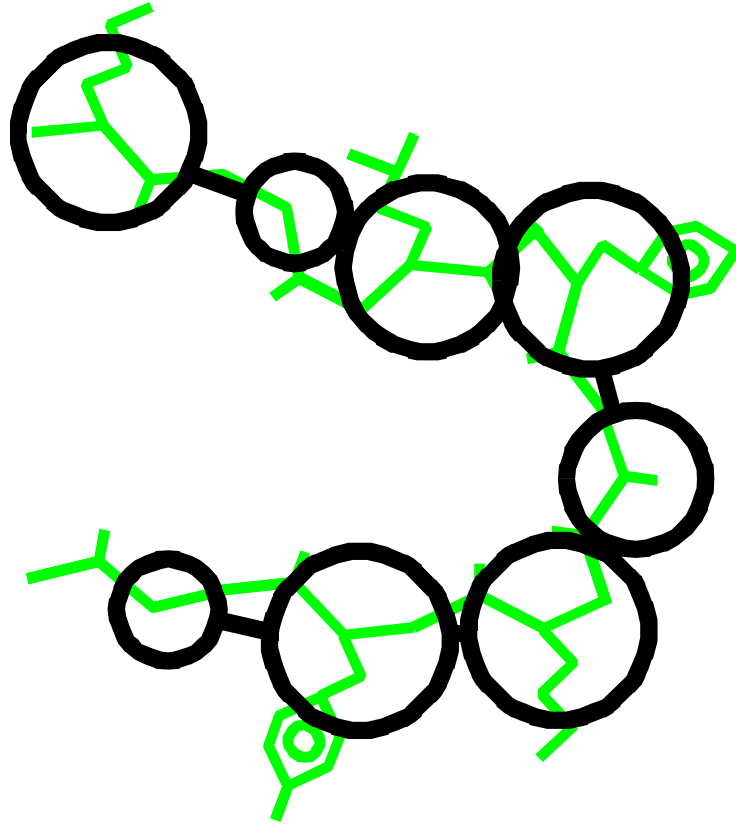
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# General implementation (easiest)

How do we represent a protein ?

- decide on number of sites per residue





# Coarse-graining (steps)

- Decide on representation
- Invent quasi-energy functions

## Our plan

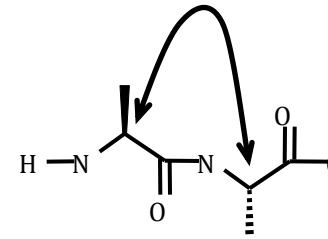
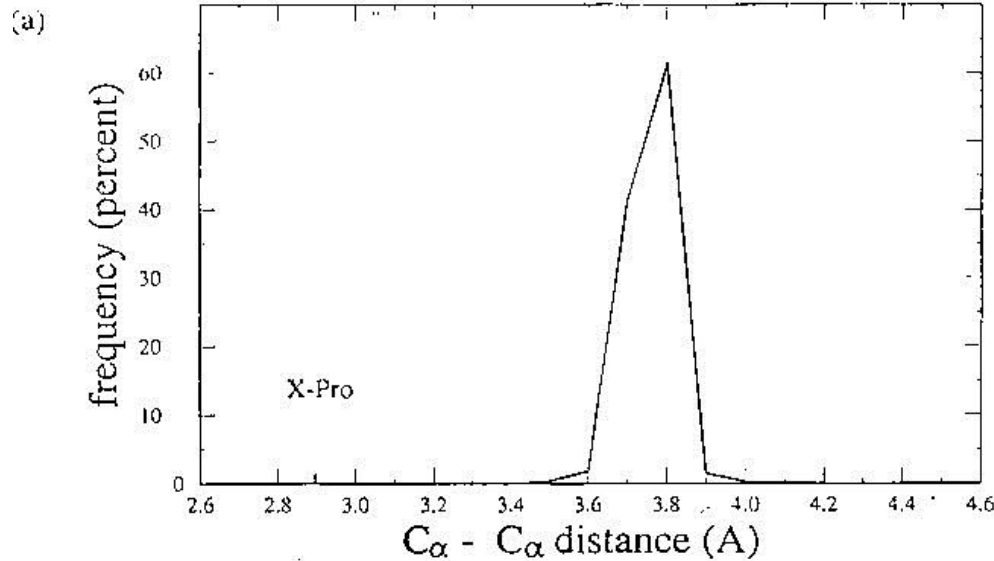
- step through some examples from literature

## Common features

- some way to maintain basic geometry
- size
- hydrophobicity ? which residues interact with each other/solvent

# Basic geometry

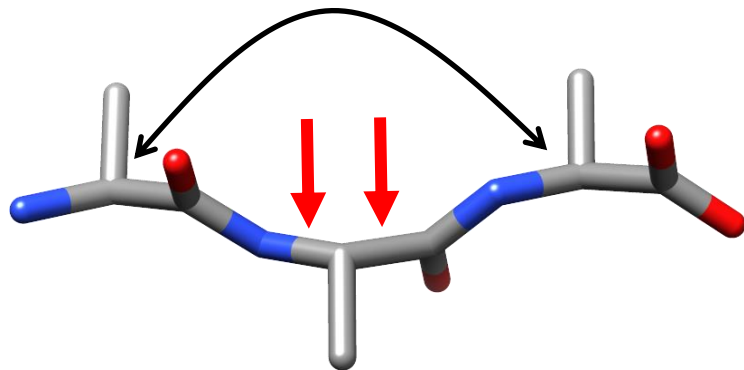
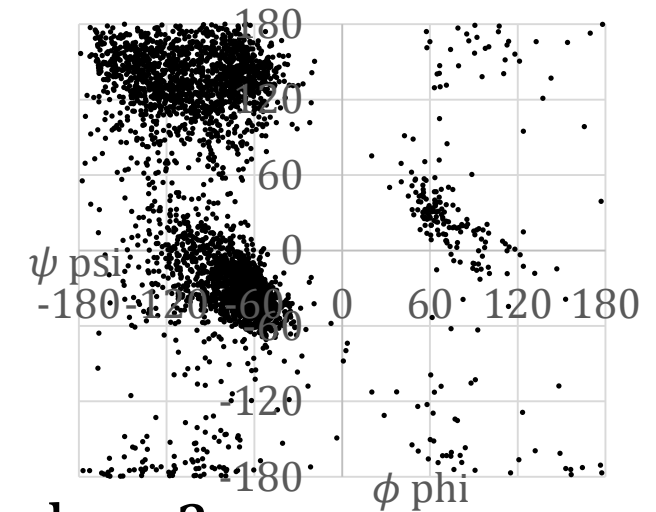
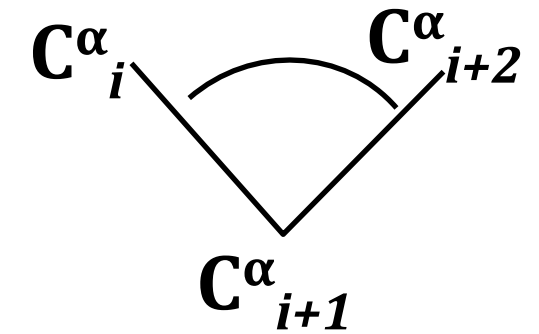
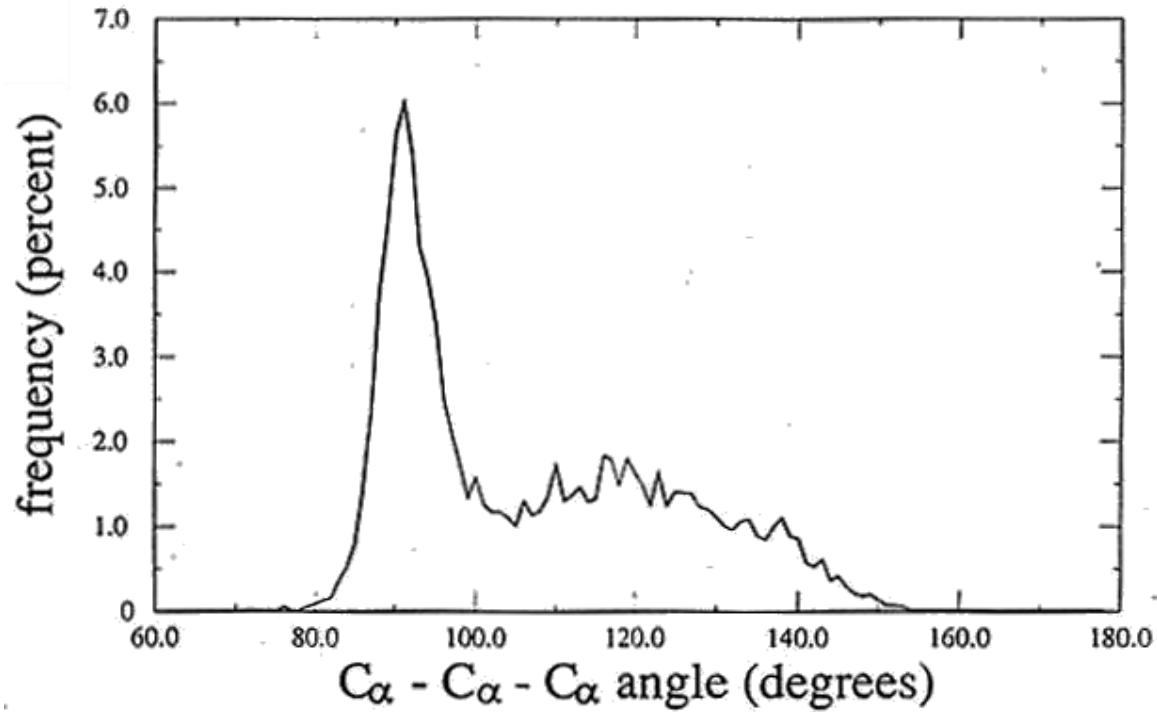
Survey protein data bank files and look at  $C\alpha$  to  $C\alpha$  distances



Conclusion is easy

- any model should fix  $C\alpha_i, i+1$  distances at 3.8 Å
- what other properties do we know ?

# $C_{i,i+2}^\alpha$ distance / angle



- why is distance less clear ?
- think of ramachandran plot

# First simple model

$n$  residues,  $n$  interaction sites  $i, i+1$  restrained ( $C^\beta$  formulation)

Overlap penalty / radii

- lys 4.3 Å, gly 2.0 Å, ... trp 5.0 Å
- $U(r_{ij}) = (\text{radius}_i + \text{radius}_j)^2 - r_{ij}^2$

force hydrophilic residues to surface, for these residues

- $U^*(r_{ij}) = (100 - d_i^2)$  where  
 $d_i$  is distance to centre, 100 is arbitrary

disulfide bonds

- very strong

residue specific interactions

- $U^{long}(r_i) = c_{ij}(r_{ij}^2 - R^2)$  where  $c_{ij}$  is residue specific
- $R$  is 10 Å for attraction, 15 Å for repulsion

# residue specific part of interaction

- $c_{ij}$  table
- features
  - hydrophobic
  - + -
  - nothing much

|     | lys | glu | ... | gly | pro | val |
|-----|-----|-----|-----|-----|-----|-----|
| lys | 25  | -10 |     | 0   | 0   | 10  |
| glu | -10 | 25  |     | 0   | 0   | 10  |
| ... |     |     |     |     |     |     |
| gly | 0   | 0   |     | 0   | 0   | 0   |
| pro | 0   | 0   |     | 0   | 0   | 0   |
| val | 10  | 10  |     | 0   | 0   | -8  |

## summary

- $i, i+1$  residue-residue
- overlap
- long range
- solvation

## where is physics ?

- solvation ?
  - term pushes some residues away from centre
- electrostatics
- hydrophobic attraction
  - by pair specific  $c_{ij}$  terms

## other properties

- smooth / continuous function
- derivative with respect to coordinates
  - (good for minimisation)

does it work ? what can one do ?

# results from first model

- try to "optimise" protein structure
- for 50 residues, maybe about 5 Å rms
  - maybe not important

Model does..

- make a hydrophobic core
- put charged and polar residues at surface
- differentiate between possible and impossible structures

Model does not reproduce

- any geometry to Å accuracy
- details of secondary structure types (not intended)
- physical pathways
- subtleties of sequence features (simplicity of  $c_{ij}$  matrix)

# Improvements to simple model

## Aim

- biggest improvement for least complication

## Possibilities

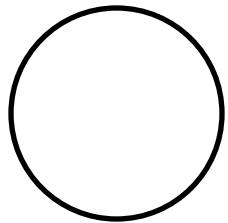
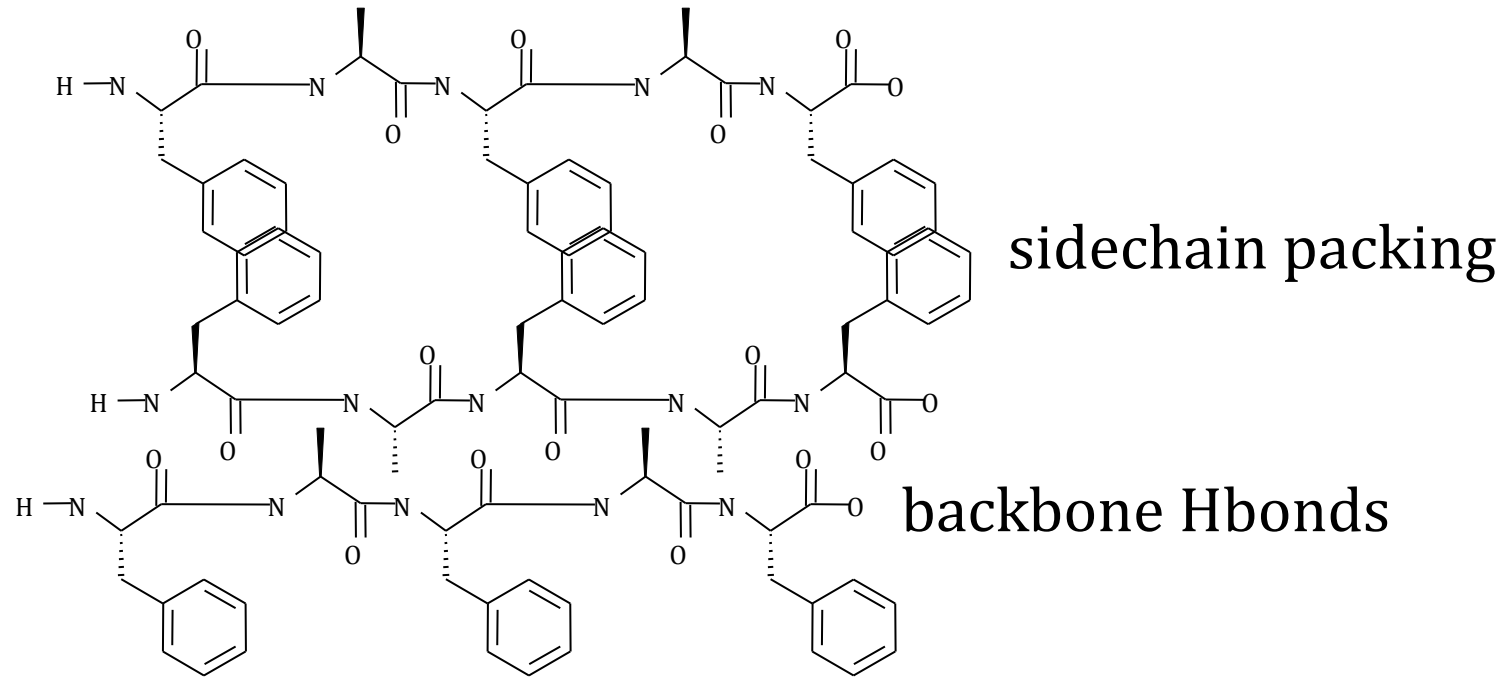
- more points per residue
- more complicated  $c_{ij}$  matrix...
- an example weakness

## Important structural features of proteins

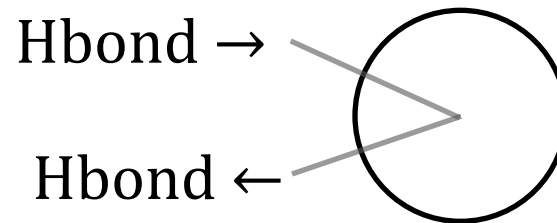
- all proteins have hydrogen bonds at backbone
- proteins differ in their sidechain interactions..



# more complicated interactions



one point residue

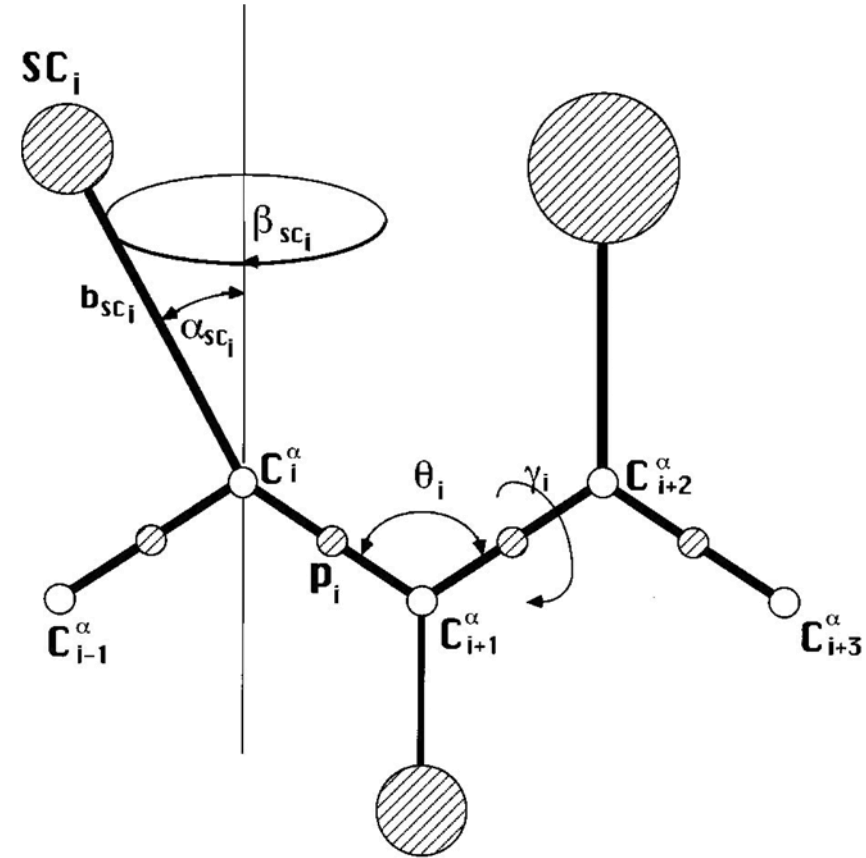


3 points per residue

# Scheraga model

3 points per residue

- 2 for interactions
  - $p_i$  is peptide bond centre
  - $SC_i$  is sidechain
- 1 for geometry
  - $C^\alpha$
- $C^\alpha - C^\alpha$  fixed at  $3.8 \text{ \AA}$

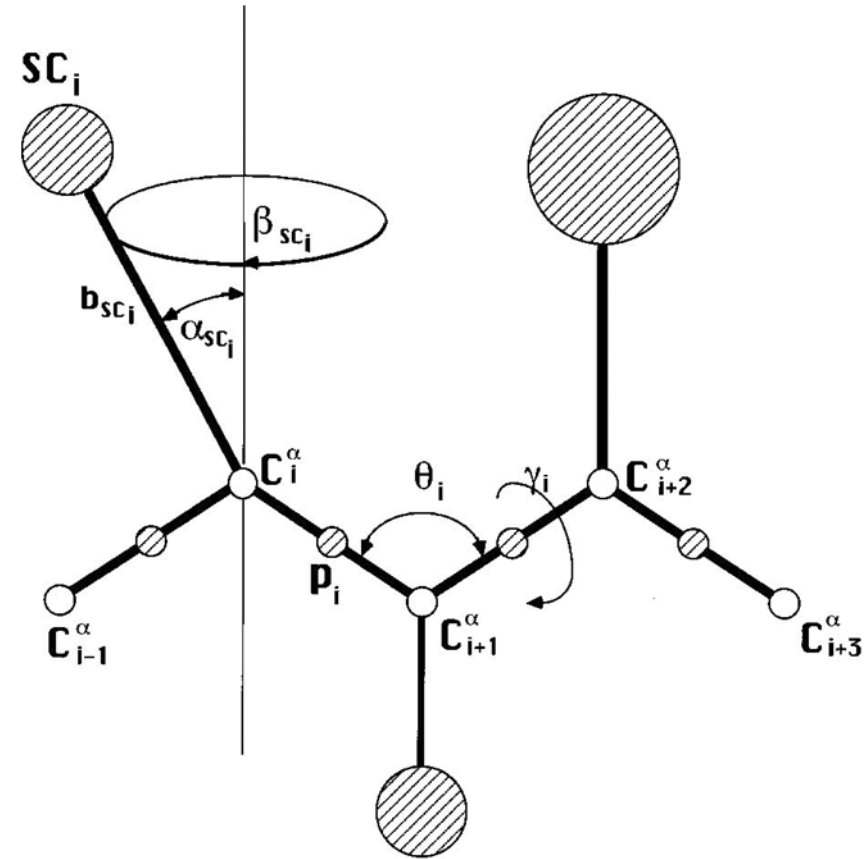


Do interaction sites correspond to atoms ?

# Terms in Scheraga model

Total quasi energy =

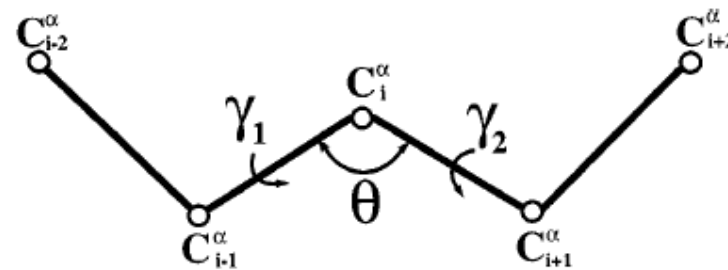
- side-chain to side-chain
- side-chain to peptide
- peptide to peptide
- torsion angle  $\gamma$
- bending of  $\theta$
- ...
  - bending  $\alpha_{sc}$



# angle between $C^\alpha$ sites

Cunning approach

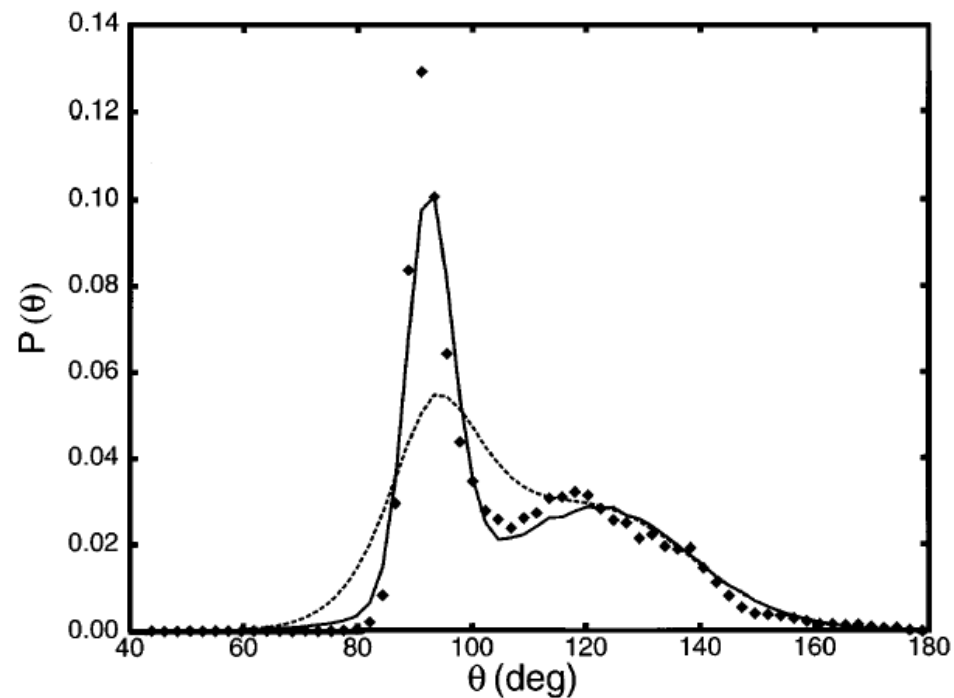
- look at  $\theta$  distribution
- model with Gaussians



then say

$$U(\theta)^{bend} = -RT \ln P(\theta)$$

where  $P(x)$  is the probability of finding a certain  $x$

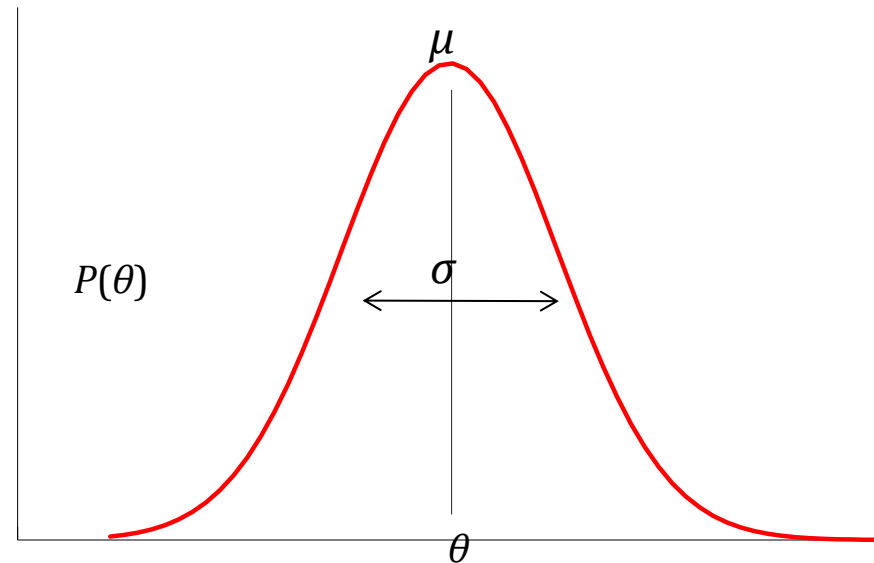


# Gaussian reminder

- get  $\mu$  and  $\sigma$  from fitting
- angle  $\theta$  depends on structure

$$P(\theta) = \frac{1}{\sigma\sqrt{2\pi}} \exp\left(\frac{-(\theta - \mu)^2}{2\sigma^2}\right)$$

- how would forces work ?
- express  $\theta$  in terms of  $r$ 's
- use  $U(\theta)^{bend} = -RT \ln P(\theta)$
- take  $\frac{dU}{d\theta} \frac{\partial \theta}{\partial \vec{r}}$



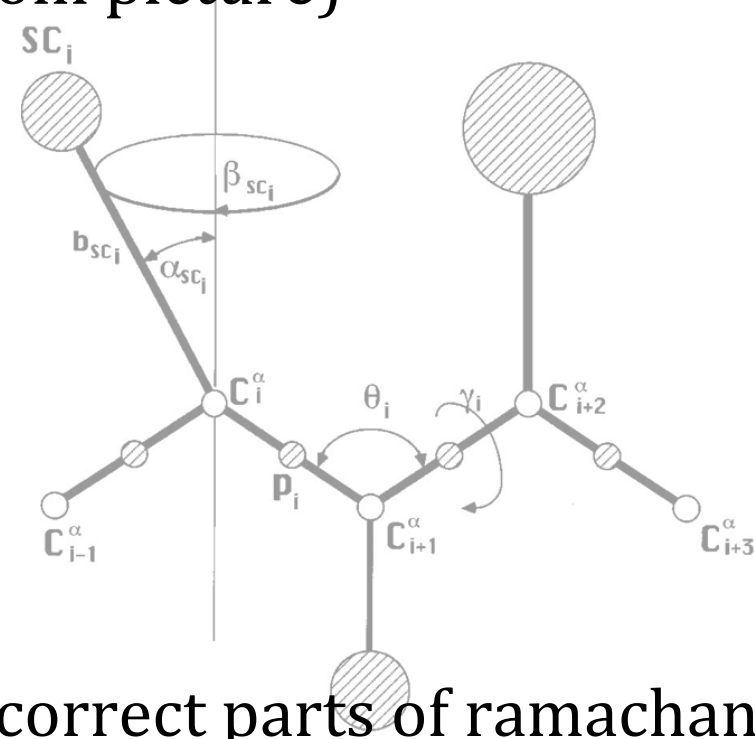
# pseudo torsion term

Like atomic torsion  $U(\gamma_i) = a_i \cos n\gamma_i + 1 + b_i \sin n\gamma_i + 1$

- $n$  varies from 3 to 6 depending on types  $i + 1, i + 2$   
(numbering from picture)

Three kinds of pair

- gly
- pro
- others



Net result ?

- residues will be positioned so as to populate correct parts of ramachandran plot
- this model will reproduce  $\alpha$ -helix and  $\beta$ -sheets

# side-chain peptide

Not so important

- mostly repulsive  $U^{sc-p}(r_{sc-p}) = kr_{sc-p}^{-6}$
- $k$  is positive, so energy goes up as particles approach

## side chain interactions

Familiar 
$$U(r_{ij}) = 4\varepsilon_{ij} \left( \left( \frac{\sigma_{ij}}{r_{ij}} \right)^{-12} - \left( \frac{\sigma_{ij}}{r_{ij}} \right)^{-6} \right)$$

- but, consider all the  $\sigma$  and  $\varepsilon$
- main result
  - some side chains like each other (big  $\varepsilon$ )
  - some pairs can be entirely repulsive (small  $\varepsilon$  big  $\sigma$ )
  - some not important (small  $\varepsilon$  small  $\sigma$ )

# more complications

Real work used

- different forms for long range interactions
- cross terms in pseudo angles

*nicht für Klausur*



# What can one do ?

Typical application

Background

- protein comparison lectures..
- different sequences have similar structure
  - can we test some structure for a sequence

Remember sequence + structure testing in modelling Übung ?

- here
  - given some possible structures for a sequence
    - can be tested with this simple force field

What can we not do ?

- physical simulations
  - think of energy barriers (not real)
  - time scale

# summary of philosophy

- Is any model better than others ?
- Each model represents something of interest
  - hydrophobic / hydrophilic separation
  - reasonably good quality structure with
    - real secondary structure
    - accurate geometry

## Main aims

- pick the simplest model which reproduces quantity of interest

## Are there bad models ?

- complicated, but not effective
- interaction sites at wrong places
  - not efficient
  - not effective

# Parameterisation..

## Problem example

- charge of an atom ?
  - can be guessed, measured ? - calculated from QM
- $\epsilon$  and  $\sigma$  in atomistic systems
  - can be taken from experiment (maybe)
  - adjust to reproduce something like density

What if a particle is a whole amino acid or sidechain ?

- is there such a thing as
- charge ?
- $\epsilon$  and  $\sigma$  ?

# Approaches to parameterisation

## General methods

- average over more detailed force field (brief)
- optimise / adjust for properties (brief)
- potentials of mean force / knowledge based (detailed)

# From detailed to coarse grain

Assume detailed model is best

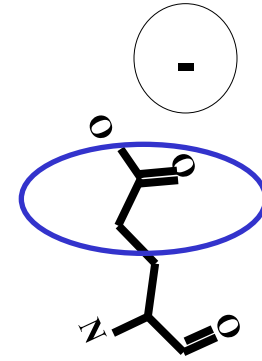
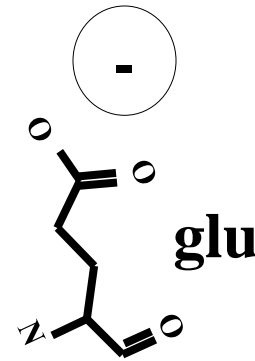
- Can we derive coarse grain properties from detailed ?

Examples – consider one or two sites per residue

- mass ? easy – add up the mass of atoms (also boring)

Charge ? not easy

- size of charge - obvious
- location ?
  - not easy
  - does this let us include polarity ? No.
- is this the right way to think about it ?...



# Averaging over details is not easy

General interaction between two residues

- will depend on orientation, distance, other neighbours
- not all orientations occur equally likely
- sensible averaging not obvious
- better approach ...

# Parameterising by adjustment / optimisation

while not happy

    move a parameter up or down

    measure happiness

for (parameter = small; parameter < big ; parameter++)

    measure happiness

Define happiness - what do you want ?

- density at equilibrium
- free energy change of some process
- distance of average protein structure from X-ray
- ....

# cost function

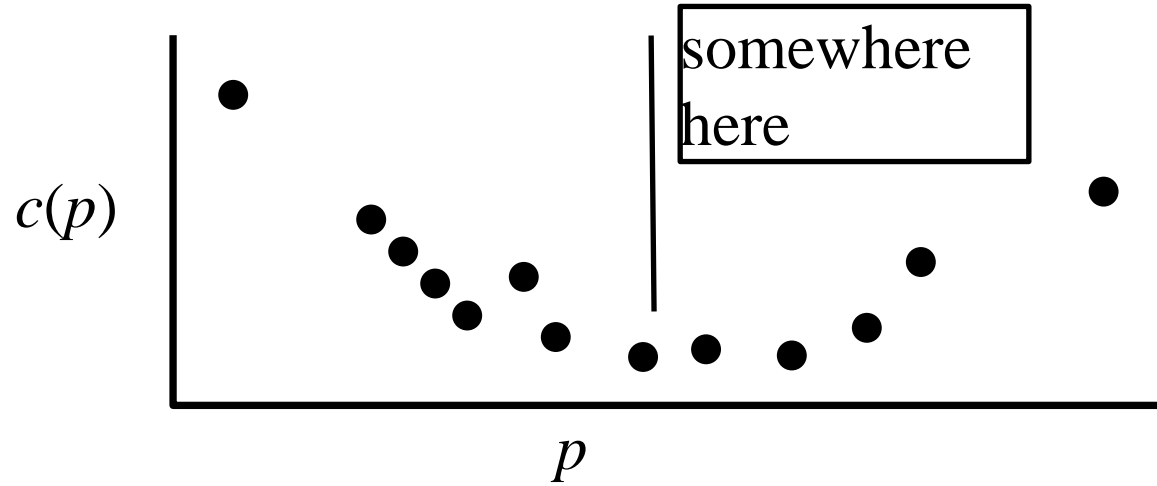
For your definition of happiness

- some measured observable  $\mathcal{A}_{obs}$ 
  - density, dielectric constant, diffusion constant, ..

From simulation with parameter  $p$

- simulate and get  $\mathcal{A}_p$
- unhappiness (cost) is a function of  $p$ , so we have  $c(p)$ 
  - $c(p) = |\mathcal{A}_{obs} - \mathcal{A}_p|$
  - or maybe  $c(p) = (\mathcal{A}_{obs} - \mathcal{A}_p)^2$
- very concrete





- each point is result from a simulation
- noise / inaccuracy, not symmetric / linear

Example  $p$  is  $\sigma$  in  $U(r_{ij}) = 4\varepsilon_{ij} \left( \left( \frac{\sigma_{ij}}{r_{ij}} \right)^{-12} - \left( \frac{\sigma_{ij}}{r_{ij}} \right)^{-6} \right)$

we would be adjusting the size of particles

# parameters optimisation – boring ? easy ?

You would not choose  $p$  values randomly

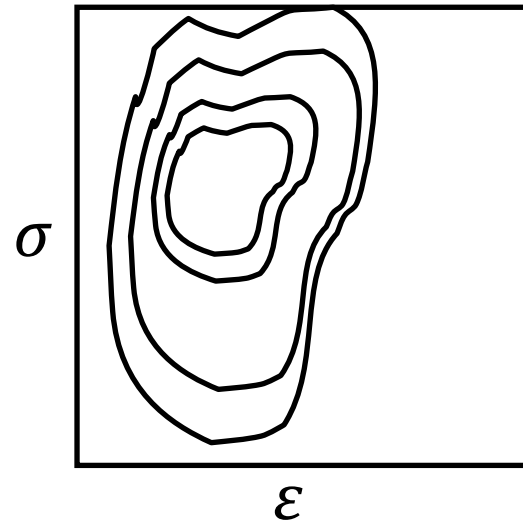
- (use a classic optimisation method)

Is this too easy and dull ?

- what you probably have is several parameters  $c(p_1, p_2)$

$$U(r_{ij}) = 4\varepsilon_{ij} \left( \left( \frac{\sigma_{ij}}{r_{ij}} \right)^{-12} - \left( \frac{\sigma_{ij}}{r_{ij}} \right)^{-6} \right)$$

- measure the error/cost in 2D space



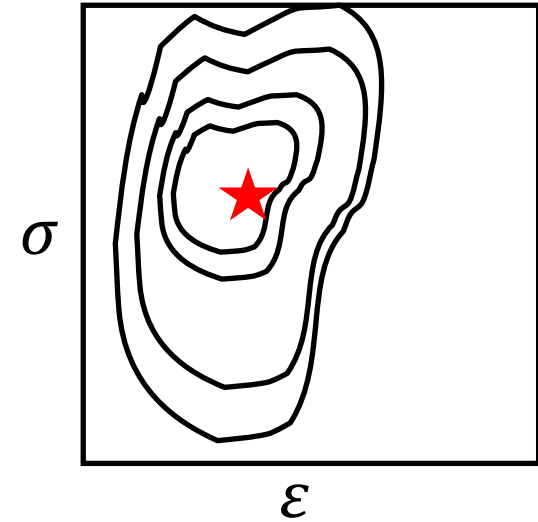
# mapping parameter space

What does this tell us ?

- find best  $\varepsilon$  and  $\sigma$
- see that  $\varepsilon$  is critical,  $\sigma$  less so

Practical implementation

- systematic search ? Inefficient
- automate the optimisation
  
- Problems...



# Problems with parameterisation

- scheme requires a believable measure of quality
- easy for two parameters
- possible for 3, 4 parameters
- very difficult for 100 parameters
  
- you optimize for density
  - diffusion, free energy changes ....
    - all broken
  - you optimise based on 10 proteins
    - test of 11<sup>th</sup> - bad results (too small training set)

# Different kind of score function

Change of style...

- questions on coarse-graining ?
- why is entropy an issue ? (numbers of particles / states)
  
- from nice ideas to dumb empiricism

# Potentials of mean force

Potential of mean force ... knowledge based score functions

- very general
- history from atomistic simulations

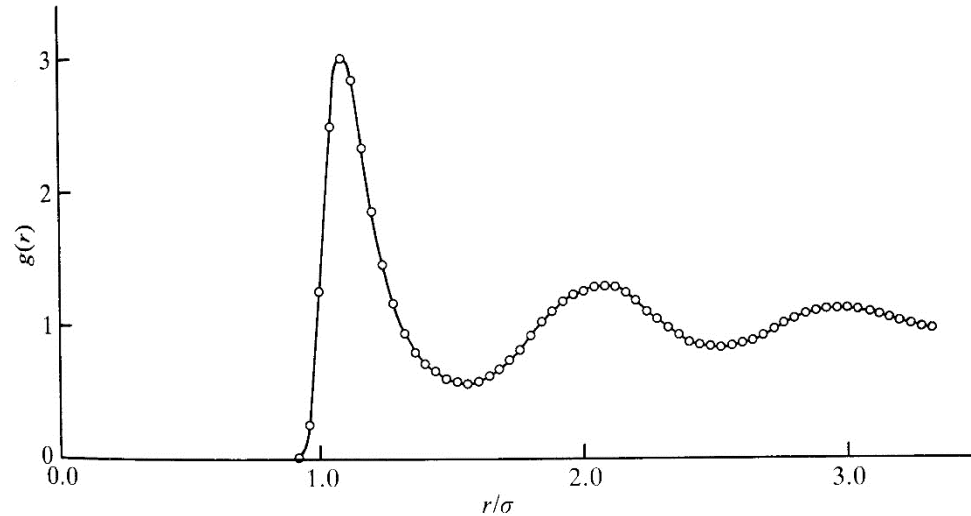
Basic idea .. easy

- from radial distribution function, to something like energy..

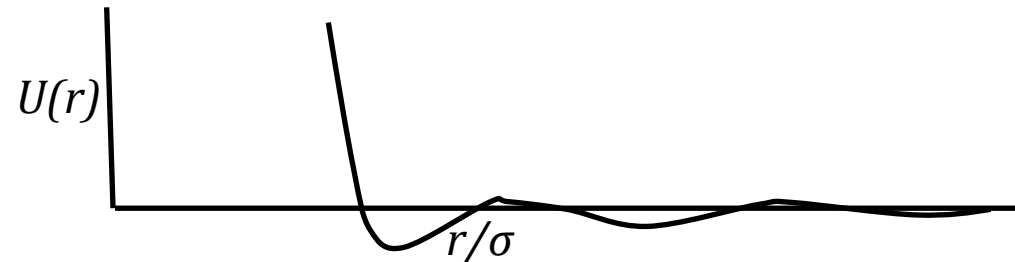
# Intuitive version of potential of mean force

Radial distribution function  $g(r)$

- probability of finding a neighbour at a certain distance



What does this suggest about energy ?

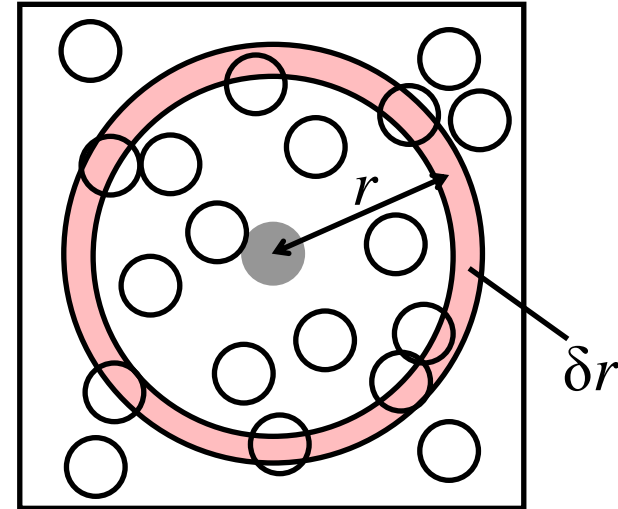


# Radial distribution function

Formal idea  $g(r) = \frac{N_{neighbours\ seen}(r)}{N_{neighbours\ expected}(r)}$

$$N_{expected} = \frac{V_{shell}}{V} N$$

- $N$  particles
- $V$  volume
- Calculating it?
  - define a shell thickness ( $\delta r$ )
  - around each particle
    - at each distance, count neighbours within shell



$$g(r) = \frac{V}{NV_{shell}} N_{shell}(r)$$



# Rationale for potentials of mean force

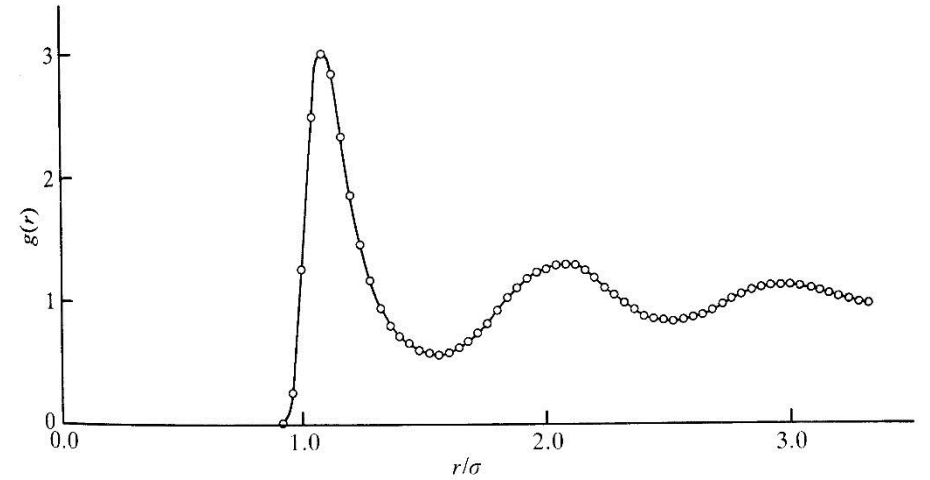
For state  $i$  compared to some reference  $x$

$$\frac{p_i}{p_x} = \frac{e^{\frac{-E_i}{kT}}}{e^{\frac{-E_x}{kT}}} = e^{\frac{E_x - E_i}{kT}}$$

$$\ln \frac{p_i}{p_x} = \frac{E_x - E_i}{kT}$$

$$\Delta E = kT \ln \frac{p_i}{p_x}$$

# Information in distribution function



Intuitive properties ?

- how likely is it that atoms get near to each other ( $< \sigma$ ) ?
- what would a crystal look like ? (very ordered)
- what if interactions are
  - very strong (compared to temperature)
  - very weak
- Seems to reflect
  - strength of interactions / order

Relate this back to energy

# Energy from $g(r)$

From statistical mechanics  $g(r) = e^{\frac{-w(r)}{kT}}$

- use work  $w(r)$  for a picture moving particle by  $r$   
so strictly  $w(r) = -kT \ln g(r)$
- already useful for looking at liquid systems

## Properties

- are we looking at potential energy  $U$  or free energy  $G$ ?
  - if our results from nature / simulation – free energy

How would we get  $g(r)$  ?

- experiment ? sometimes
- simulation – easy – simulate at high resolution

## Assumptions

- our system is at equilibrium

# Generalising ideas of potential of mean force

What else can we do ?

- think of more interesting system ( $\text{H}_2\text{O}$ )

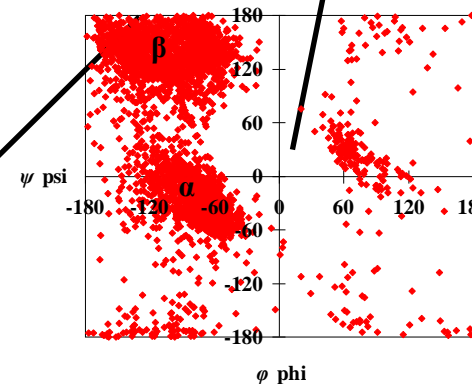
Would we express our function in terms of O ? H ?

- both valid
- could consider work done bringing an O to O, O to H, H to H
  - for fun on next page

More general..

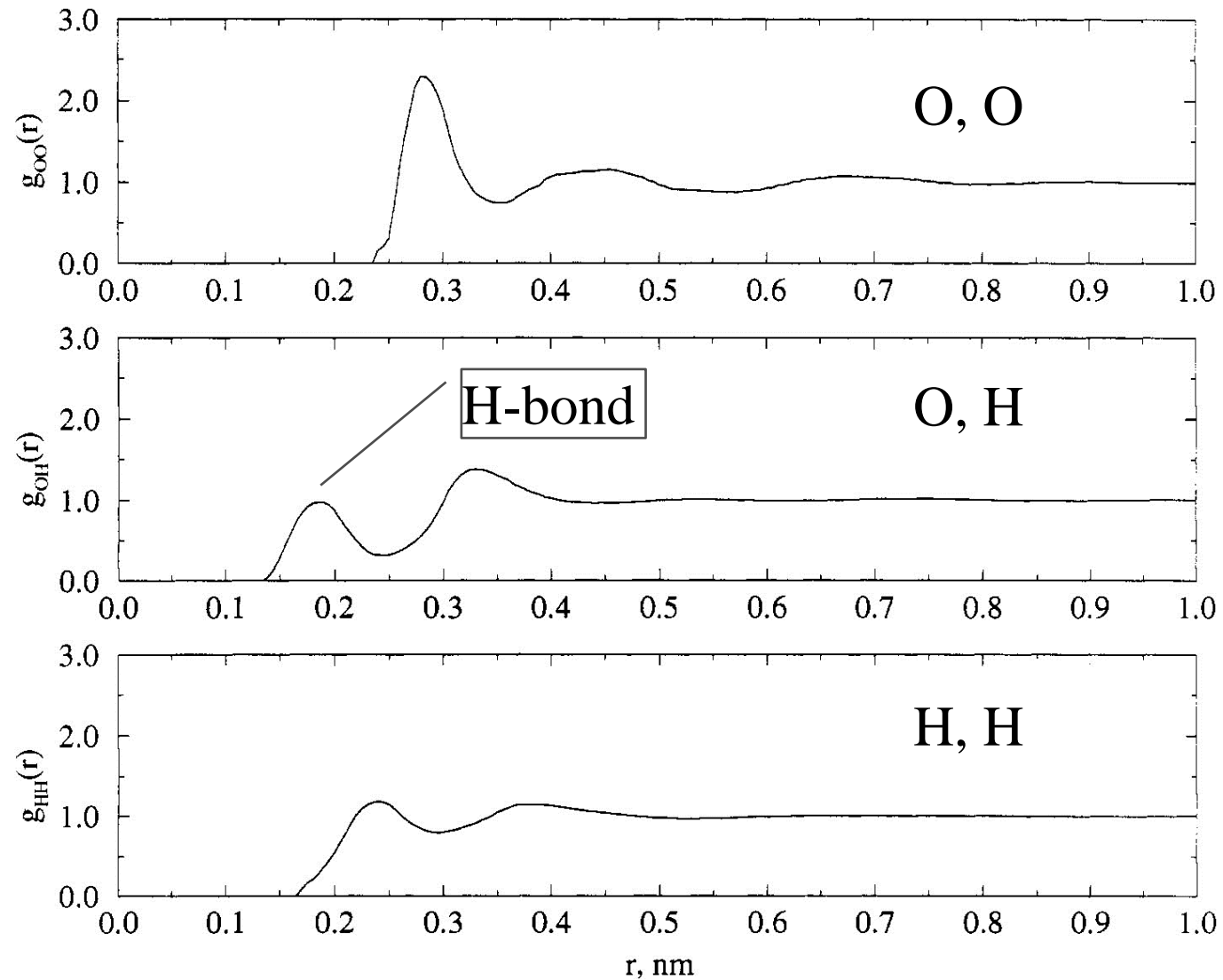
- are we limited to distances ? No
- example – ramachandran plot

high probability /  
low energy



low probability /  
high energy

# radial distribution function (water)



# Reformulating for our purposes

Can one use these ideas for proteins ?

Our goal ?

- a force field / score function for deciding if a protein is happy
- work with particles / interaction sites
- slightly different formulation
  - if I see a pair of particles close to each other,
    - is this more or less likely than random chance ?
  - treat pieces of protein like a gas
  - care about types of particles (unlike simple liquid)

Let us define...

# Score energy formulation

$$W_{AB}(r) = -RT \ln \left( \frac{N_{AB}^{obs}(r \pm \delta r)}{N_{AB}^{exp}(r \pm \delta r)} \right)$$

$N_{AB}^{obs}$  how many times do we see

- particles of types A and B
- distance  $r$  given some range  $\delta r$

$N_{AB}^{exp}$  how often would you expect to see AB pair at  $r$  ?

- remember Boltzmann statistics

This is not yet an energy / score function !

- it is how to build one

Intuitive version

- $\text{Cl}^-$  and  $\text{Na}^+$  in water like to interact (distance  $r^0$ )
- $N_{AB}^{obs}$  is higher than random particles
- $W_{\text{ClNa}}(r)$  is more negative at  $r^0$

# Details of formulation

$$W_{AB}(r) = -RT \ln \left( \frac{N_{AB}^{obs}(r \pm \delta r)}{N_{AB}^{exp}(r \pm \delta r)} \right)$$

- looks easy, but what is  $N^{exp}$  ?

Maybe fraction of particles is a good approximation

$$N_{AB}^{exp} = N_{all} X_{Na} X_{Cl} \quad (\text{use mole fractions})$$

- use this idea to build a protein force field / score function



# Protein score function

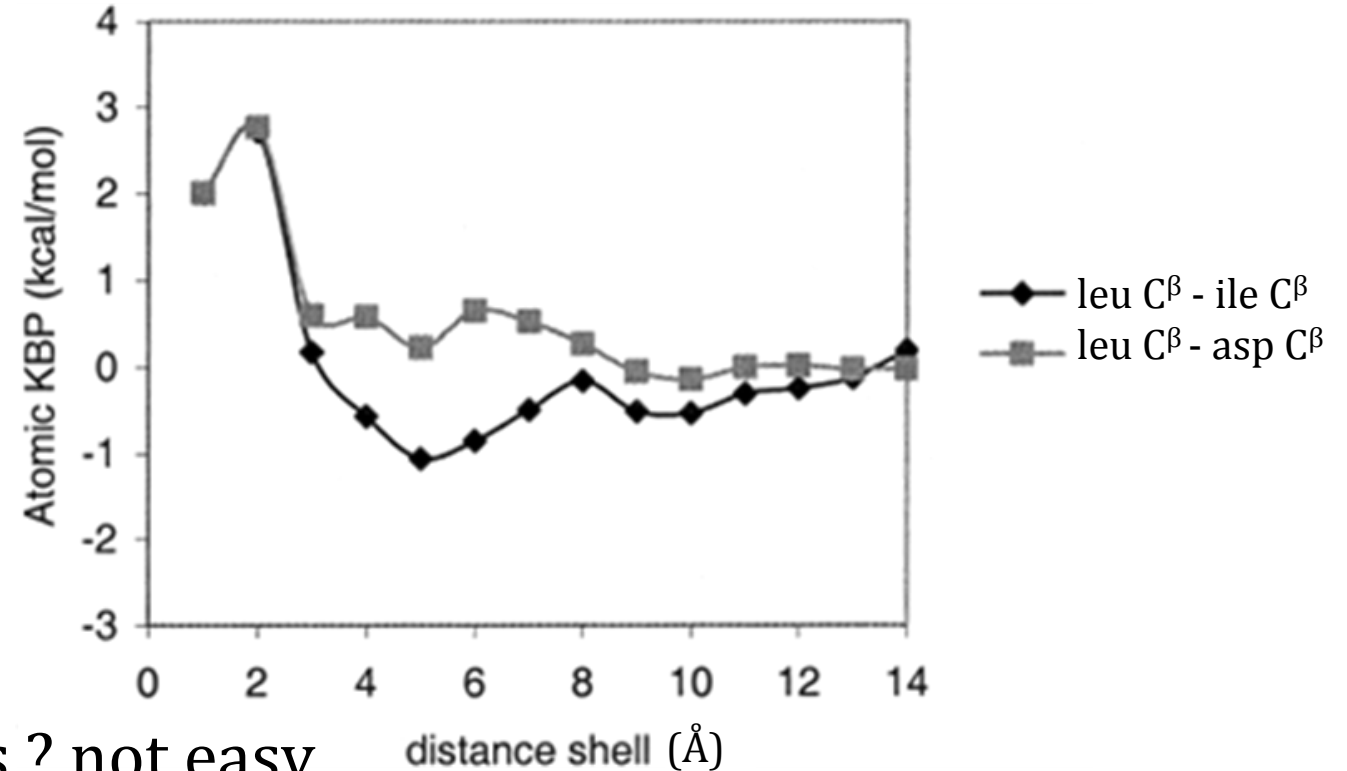
Arbitrarily

- define interaction sites as one per residue
  - maybe at  $C^\alpha$  or  $C^\beta$
- collect set of structures from protein data bank
- define a distance (4 Å) and range ( $\pm 0.5$  Å)
- count how often do I see
  - gly-gly at this range, gly-ala, gly-X, X-Y ...
    - gives me  $N^{obs}$
  - how many pairs of type gly-gly, gly-ala, gly-X, X-Y... are there ?
    - gives me  $N^{exp}$
  - repeat for 5 Å, 6 Å, ...
- resulting score function...

# final score function

For every type of interaction AB ( $20 \times 21 / 2$ )

- set of  $W_{AB}(r)$



All ingredients in place

- can we use this for simulations ? not easy
- can we use to score a protein ? yes

Names

- Boltzmann-based, knowledge based

# Applying knowledge-based score function

Take your protein

- for every pair of residues
  - calculate  $C^\beta$   $C^\beta$  distance (for example)
  - look up type of residues (ala-ala, trp-ala, ...)
  - look up distance range
  - add in value from table
- what is intuitive result from a
  - a sensible protein / a misfolded protein ?
- is this a real force field ? yes
- is this like the atomistic ones ? no
  - there are no derivatives  $\left(\frac{dU}{dr}\right)$
  - it is not necessarily defined for all coordinates

# Practical Problems Boltzmann score functions

Do we have enough data ?

- how common are Asp-Asp pairs at short distance ?

How should we pick distance ranges ?

- small bins ( $\delta r$ ) give a lot of detail, but there is less data

What are my interaction sites ?

- $C^\alpha$  ?  $C^\beta$  ? both ?

Data bias

- Can I ever find a representative set of proteins ?
  - PDB is a set of proteins which have been crystallised

# Reminder

- we want low-resolution score functions
- if we work in a Boltzmann framework, we work with real energies
- everything ends up as  $\frac{p_i}{p_j} = e^{-\frac{\Delta E}{RT}}$  or here  $\Delta E = -RT \ln \frac{p_i}{p_j}$  or  $\Delta E = -RT \ln \frac{N_{obs}}{N_{exp}}$
- we are comparing against what you expect from random events without interactions  $p_j$
- work with  $\text{kJ mol}^{-1}$ , we can
  - make real energetic predictions (kinetics, equilibria)
  - combine with other energy terms

# Problems of Principle

## Boltzmann statistics

- is the protein data bank a set of structures at equilibrium ?

Is this a potential of mean force ? Think of Na, Cl example

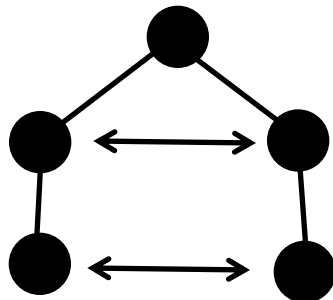
- that is a valid PMF since we can average over the system

Energy / Free energy

- how real ?

$N^{exp}$  ? how should it be calculated ?

- is the fraction of amino acid a good estimate ? No.
- there are well known effects.. Examples



$i, i+2$

$i, i+4$  very different statistics

# Boltzmann based scores: improvements / applications

- collect data separately for  $(i, i+2)$ ,  $(i, i+3)$ , ...
  - problems with sparse (missing) data
- collect data on angles
- collect data from different atoms
- collect protein – small molecule data

## Are these functions useful ?

- not perfect, not much good for simulation
- we can take any coordinates and calculate a score
  - directly reflects how likely the coordinates are
- threading / fold recognition

# Parameterising summary

- Inventing a score function / force field needs parameters
- totally invented (Crippen, Kuntz, ...)
- optimisation / systematic search
- statistics + Boltzmann distribution



# Summary of low-resolution force fields

## Properties

- do we always need a physical basis ?
- do we need physical score (energy) ?

## Questions

- pick interaction sites
- pick interaction functions / tables

## What is your application ?

- simulation
  - reproducing a physical phenomenon (folding, binding)
- scoring coordinates

## Parameterisation

- Averaging, optimisation, potentials of mean force

Next – less physical